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Description Calibration of penalized criteria for model selection. The calibration methods available are based on the slope heuristics.

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capushe-package

Capushe

Description

This package includes functions for model selection via penalization. The model selection criterion has the following form: $\gamma_n(\hat{s}_m) + scoef \times \kappa \times pen_{shape}(m)$. Two algorithms based on the slope heuristics are proposed to calibrate the parameter κ in the penalty: the [data-driven slope estimation algorithm \(DDSE\)](#) and the [dimension jump algorithm \(Djump\)](#).

Details

The data-driven slope estimation algorithm and the dimension jump algorithm are respectively implemented into the [DDSE](#) function and the [Djump](#) function. Some classes are defined for the outputs of [DDSE](#) and [Djump](#) and a [graphical](#) display is available for each one of these two classes. [DDSE](#) and [Djump](#) are both included in the [capushe](#) function which is the main function of the package.

Author(s)

Sylvain Arlot, Vincent Brault, Jean-Patrick Baudry, Cathy Maugis and Bertrand Michel.

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References

<http://www.math.univ-toulouse.fr/~maugis/CAPUSHE.html>

<http://www.math.u-psud.fr/~brault/capushe.html>

Article: Baudry, J.-P., Maugis, C. and Michel, B. (2011) Slope heuristics: overview and implementation. *Statistics and Computing*, to appear. doi: 10.1007/s11222-011-9236-1

See Also

[Djump](#) and [DDSE](#) for model selection algorithms based on the slope heuristics. [plot](#) for a graphical display of the two algorithms. [validation](#) to check that the slope heuristics can be applied confidently.

Examples

```
data(datacapushe)
## capushe returns the same model with DDSE and Djump:
capushe(datacapushe)
## capushe also returns the model selected by AIC and BIC
capushe(datacapushe,n=1000)
## Djump only
Djump(datacapushe)
## DDSE only
DDSE(datacapushe)
## Graphical representations
```

```

plot(Djump(datacapushe))
plot(DDSE(datacapushe))
plot(capushe(datacapushe))
## Validation procedure
data(datapartialcapushe)
capushepartial=capushe(datapartialcapushe)
plot(capushepartial)
## Additional data
data(datavalidcapushe)
validation(capushepartial,datavalidcapushe) ## The slope heuristics should not
## be applied for datapartialcapushe.

```

BICAICcapushe

AICcapushe and BICcapushe

Description

These functions return the model selected by the Akaike Information Criterion (AIC) and the Bayesian Information Criterion (BIC).

Usage

```

AICcapushe(data, n)
BICcapushe(data, n)

```

Arguments

data	data is a matrix or a data.frame with four columns of the same length and each line corresponds to a model: <ol style="list-style-type: none"> 1. The first column contains the model names. 2. The second column contains the penalty shape values. 3. The third column contains the model complexity values. 4. The fourth column contains the minimum contrast value for each model.
n	n is the sample size.

Details

The penalty shape value should be increasing with respect to the complexity value (column 3). The complexity values have to be positive. n is necessary to compute AIC and BIC criteria. n is the size of sample used to compute the contrast values given in the data matrix. Do not confuse n with the size of the model collection which is the number of rows of the data matrix.

Value

model	The model selected by AIC or BIC.
AIC	The corresponding value of AIC (for AICcapushe only).
BIC	The corresponding value of BIC (for BICcapushe only).

Author(s)

Vincent Brault

References

<http://www.math.univ-toulouse.fr/~maugis/CAPUSHE.html>

<http://www.math.u-psud.fr/~brault/capushe.html>

Article: Baudry, J.-P., Maugis, C. and Michel, B. (2011) Slope heuristics: overview and implementation. *Statistics and Computing*, to appear. doi: 10.1007/s11222-011-9236-1

See Also

[capushe](#) for a model selection function including AIC, BIC, the [DDSE](#) algorithm and the [Djump](#) algorithm.

Examples

```
data(datacapushe)
AICcapushe(datacapushe, n=1000)
BICcapushe(datacapushe, n=1000)
```

capushe

Calibrating Penalties Using Slope HEuristics (CAPUSHE)

Description

The capushe function proposes two algorithms based on the slope heuristics to calibrate penalties in the context of model selection via penalization.

Usage

```
capushe(data, n=0, pct=0.15, point=0, psi.rlm=psi.bisquare, coef=2,
        Careajump=0, Ctresh=0)
```

Arguments

data	data is a matrix or a data.frame with four columns of the same length and each line corresponds to a model: <ol style="list-style-type: none"> 1. The first column contains the model names. 2. The second column contains the penalty shape values. 3. The third column contains the model complexity values. 4. The fourth column contains the minimum contrast value for each model.
n	n is the sample size.

pct	Minimum percentage of points for the plateau selection. See DDSE for more details.
point	Minimum number of point for the plateau selection (See DDSE for more details). If point is different from 0, pct is obsolete.
psi.rlm	Weight function used by rlm . See DDSE for more details. <code>psi.rlm="lm"</code> for non robust linear regression.
scoef	Ratio parameter. Default value is 2.
Careajump	Constant of jump area (See Djump for more details). Default value is 0 (no area).
Ctresh	Maximal treshold for the complexity associated to the penalty coefficient (See Djump for more details). Default value is 0 (Maximal jump selected as the greater jump).

Details

The model \hat{m} selected by the procedure fulfills

$$\hat{m} = \operatorname{argmin} \gamma_n(\hat{s}_m) + \text{scoef} \times \kappa \times \text{pen}_{\text{shape}}(m)$$

where

- κ is the penalty coefficient.
- γ_n is the empirical contrast.
- \hat{s}_m is the estimator for the model m .
- *scoef* is the ratio parameter.
- *pen_{shape}* is the penalty shape.

The *capushe* function calls the functions [DDSE](#) and [Djump](#) to calibrate κ , see the description of these functions for more details. In the case of equality between two penalty shape values, only the model with the smallest contrast is considered.

Value

@DDSE	A list returned by the DDSE function.
@DDSE@model	The model selected by the DDSE function.
@DDSE@kappa	The vector of the successive slope values.
@DDSE@ModelHat	A list providing details about the model selected by the DDSE function.
@DDSE@interval	A list about the "slope interval" corresponding to the plateau selected in DDSE . See DDSE for more details.
@DDSE@graph	A list computed for the plot function.
@Djump	A list returned by the Djump function.
@Djump@model	The model selected by the Djump function.
@Djump@ModelHat	A list providing details about the model selected by the Djump function.
@Djump@graph	A list computed for the plot function.
@AIC_capushe	A list returned by the AICcapushe function.
@BIC_capushe	A list returned by the BICcapushe function.
@n	Sample size.

Author(s)

Vincent Brault

References

<http://www.math.univ-toulouse.fr/~maugis/CAPUSHE.html>

<http://www.math.u-psud.fr/~brault/capushe.html>

Article: Baudry, J.-P., Maugis, C. and Michel, B. (2011) Slope heuristics: overview and implementation. *Statistics and Computing*, to appear. doi: 10.1007/s11222-011-9236-1

See Also

[Djump](#), [DDSE](#), [AIC](#) or [BIC](#) to use only one of these model selection functions. [plot](#) for graphical displays of DDSE and Djump.

Examples

```
data(datacapushe)
capushe(datacapushe)
capushe(datacapushe, 1000)
```

datacapushe

datacapushe

Description

A dataframe example for the [capushe package](#) based on a simulated Gaussian mixture dataset in \mathbb{R}^3 .

Usage

```
data(datacapushe)
```

Format

A data frame with 50 rows (models) and the following 4 variables:

`model` a character vector: model names.

`pen` a numeric vector: model penalty shape values.

`complexity` a numeric vector: model complexity values.

`contrast` a numeric vector: model contrast values.

Details

The simulated dataset is composed of $n = 1000$ observations in \mathbf{R}^3 . It consists of an equiprobable mixture of three large "bubble" groups centered at $\nu_1 = (0, 0, 0)$, $\nu_2 = (6, 0, 0)$ and $\nu_3 = (0, 6, 0)$ respectively. Each bubble group j is simulated from a mixture of seven components according to the following density distribution:

$$x \in \mathbf{R}^3 \rightarrow 0.4\Phi(x|\mu_1 + \nu_j, I_3) + \sum_{k=2}^7 0.1\Phi(x|\mu_k + \nu_j, 0.1I_3)$$

with $\mu_1 = (0, 0, 0)$, $\mu_2 = (0, 0, 1.5)$, $\mu_3 = (0, 1.5, 0)$, $\mu_4 = (1.5, 0, 0)$, $\mu_5 = (0, 0, -1.5)$, $\mu_6 = (0, -1.5, 0)$ and $\mu_7 = (-1.5, 0, 0)$. Thus the distribution of the dataset is actually a 21-component Gaussian mixture.

A model collection of spherical Gaussian mixtures is considered and the dataframe `datacapushe` contains the maximum likelihood estimations for each of these models. The number of free parameters of each model is used for the complexity values and pen_{shape} is defined by this complexity divided by n .

`datapartialcapushe` and `datavalidcapushe` can be used to run the `validation` function. `datapartialcapushe` only contains the models with less than 21 components. `datavalidcapushe` contains three models with 30, 40 and 50 components respectively.

Source

<http://www.math.univ-toulouse.fr/~maugis/CAPUSHE.html>

References

Article: Baudry, J.-P., Maugis, C. and Michel, B. (2011) Slope heuristics: overview and implementation. *Statistics and Computing*, to appear. doi: 10.1007/s11222-011-9236-1

Examples

```
data(datacapushe)
capushe(datacapushe, n=1000)
## BIC, DDSE and Djump all three select the true model
plot(capushe(datacapushe))
## Validation:
data(datapartialcapushe)
capushepartial=capushe(datapartialcapushe)
data(datavalidcapushe)
validation(capushepartial, datavalidcapushe) ## The slope heuristics should not
## be applied for datapartialcapushe.
```

Description

DDSE is a model selection function based on the slope heuristics.

Usage

```
DDSE(data, pct = 0.15, point = 0, psi.rlm = psi.bisquare, scoef = 2)
```

Arguments

<code>data</code>	data is a matrix or a data.frame with four columns of the same length and each line corresponds to a model: <ol style="list-style-type: none"> 1. The first column contains the model names. 2. The second column contains the penalty shape values. 3. The third column contains the model complexity values. 4. The fourth column contains the minimum contrast value for each model.
<code>pct</code>	Minimum percentage of points for the plateau selection. It must be between 0 and 1. Default value is 0.15.
<code>point</code>	Minimum number of point for the plateau selection. If point is different from 0, pct is obsolete.
<code>psi.rlm</code>	Weight function used by <code>rlm</code> . <code>psi.rlm="lm"</code> for non robust linear regression.
<code>scoef</code>	Ratio parameter. Default value is 2.

Details

Let M be the model collection and $P = \{pen_{shape}(m), m \in M\}$. The DDSE algorithm proceeds in four steps:

1. If several models in the collection have the same penalty shape value (column 2), only the model having the smallest contrast value $\gamma_n(\hat{s}_m)$ (column 4) is considered.
2. For any $p \in P$, the slope $\hat{\kappa}(p)$ (argument `@kappa`) of the linear regression (argument `psi.rlm`) on the couples of points $\{(pen_{shape}(m), -\gamma_n(\hat{s}_m)); pen_{shape}(m) \geq p\}$ is computed.
3. For any $p \in P$, the model fulfilling the following condition is selected:
$$\hat{m}(p) = \operatorname{argmin} \gamma_n(\hat{s}_m) + scoef \times \hat{\kappa}(p) \times pen_{shape}(m).$$
This gives an increasing sequence of change-points $(p_i)_{1 \leq i \leq I+1}$ (output `@ModelHat$point_breaking`). Let $(N_i)_{1 \leq i \leq I}$ (output `@ModelHat$number_plateau`) be the lengths of each "plateau".
4. If point is different from 0, let $\hat{i} = \max \{1 \leq i \leq I; N_i \geq point\}$ else let $\hat{i} = \max \{1 \leq i \leq I; N_i \geq pct \sum_{l=1}^I N_l\}$ (output `@ModelHat$imax`). The model $\hat{m}(p_{\hat{i}})$ (output `@model`) is finally returned.

The "slope interval" is the interval $[a, b]$ where $a = \inf\{\hat{\kappa}(p), p \in [p_{\hat{i}}, p_{\hat{i}+1}] \cap P\}$ and $b = \sup\{\hat{\kappa}(p), p \in [p_{\hat{i}}, p_{\hat{i}+1}] \cap P\}$.

Value

<code>@model</code>	The model selected by the DDSE algorithm.
<code>@kappa</code>	The vector of the successive slope values.
<code>@ModelHat</code>	A list describing the algorithm.
<code>@ModelHat\$model_hat</code>	The vector of preselected models $\hat{m}(p)$.

@ModelHat\$point_breaking
The vector of the breaking points $(p_i)_{1 \leq i \leq I+1}$.

@ModelHat\$number_plateau
The vector of the lengths $(N_i)_{1 \leq i \leq I}$.

@ModelHat\$imax The rank \hat{i} of the selected plateau.

@interval A list about the "slope interval".

@interval\$interval
The slope interval.

@interval\$percent_of_points
The proportion $N_{\hat{i}} / \sum_{l=1}^I N_l$.

@graph A list computed for the `plot` method.

Author(s)

Vincent Brault

References

<http://www.math.univ-toulouse.fr/~maugis/CAPUSHE.html>

<http://www.math.u-psud.fr/~brault/capushe.html>

Article: Baudry, J.-P., Maugis, C. and Michel, B. (2011) Slope heuristics: overview and implementation. *Statistics and Computing*, to appear. doi: 10.1007/s11222-011-9236-1

See Also

`capushe` for a model selection function including `AIC`, `BIC`, the DDSE algorithm and the `Djump` algorithm. `plot` for graphical displays of the DDSE algorithm and the `Djump` algorithm.

Examples

```
data(datacapushe)
DDSE(datacapushe)
plot(DDSE(datacapushe))
## DDSE with "lm" for the regression
DDSE(datacapushe,psi.rlm="lm")
```

Djump

Model selection by dimension jump

Description

Djump is a model selection function based on the slope heuristics.

Usage

```
Djump(data,coef=2,Careajump=0,Ctresh=0)
```

Arguments

data	data is a matrix or a data.frame with four columns of the same length and each line corresponds to a model: <ol style="list-style-type: none"> 1. The first column contains the model names. 2. The second column contains the penalty shape values. 3. The third column contains the model complexity values. 4. The fourth column contains the minimum contrast value for each model.
scoef	Ratio parameter. Default value is 2.
Careajump	Constant of jump area. Default value is 0 (no area). In practice, it is advisable to take $Careajump = \sqrt{\frac{\log(n)}{n}}$ where n is the number of observations.
Ctresh	Maximal treshold for the complexity associated to the penalty coefficient. Default value is 0 (Maximal jump selected as the greatest jump). In practice, it is advisable to take $Ctresh = \frac{n}{\log(n)}$ where n is the number of observations.

Details

The Djump algorithm proceeds in three steps:

1. For all $\kappa > 0$, compute
$$m(\kappa) \in \operatorname{argmin}_{m \in M} \{\gamma_n(\hat{s}_m) + \kappa \times pen_{shape}(m)\}$$
This gives a decreasing step function $\kappa \mapsto C_{m(\kappa)}$.
2. Find $\hat{\kappa}$ such that $C_{m(\hat{\kappa})}$ corresponds to the greatest jump of complexity if $C_{tresh} = 0$ else $\hat{\kappa}$ such that
$$\hat{\kappa} = \inf\{\kappa > 0 : C_{m(\kappa)} \leq Ctresh\}.$$
3. Select $\hat{m} = m(scoef \times \hat{\kappa})$ (output @model).

Arlot has proposed a jump area containing the maximal jump defined by :

$$[\kappa(1 - Careajump); \kappa(1 + Careajump)].$$

If $Careajump > 0$, Djump return the area with the greatest jump. In practice, it is advisable to take $Careajump = \frac{\log(n)}{n}$ where n is the number of observations.

Value

@model	The model selected by the dimension jump method.
@ModelHat	A list describing the algorithm.
@ModelHat\$jump	The vector of jump heights.
@ModelHat\$kappa	The vector of the values of κ at each jump.
@ModelHat\$model_hat	The vector of the selected models $m(\kappa)$ by the jump.
@ModelHat\$JumpMax	The location of the greatest jump.
@ModelHat\$Kopt	$\kappa_{opt} = scoef \hat{\kappa}$.
@graph	A list computed for the <code>plot</code> method.

Author(s)

Vincent Brault

References<http://www.math.univ-toulouse.fr/~maugis/CAPUSHE.html><http://www.math.u-psud.fr/~brault/capushe.html>

Article: Baudry, J.-P., Maugis, C. and Michel, B. (2011) Slope heuristics: overview and implementation. *Statistics and Computing*, to appear. doi: 10.1007/s11222-011-9236-1

See Also

[capushe](#) for a model selection function including [AIC](#), [BIC](#), the [DDSE](#) algorithm and the [Djump](#) algorithm. [plot](#) for a graphical display of the [DDSE](#) algorithm and the [Djump](#) algorithm.

Examples

```
data(datacapushe)
Djump(datacapushe)
plot(Djump(datacapushe))
Djump(datacapushe, Careajump=sqrt(log(1000)/1000))
plot(Djump(datacapushe, Careajump=sqrt(log(1000)/1000)))
Djump(datacapushe, Ctresh=1000/log(1000))
plot(Djump(datacapushe, Ctresh=1000/log(1000)))
```

plot-methods

Plot for capushe

Description

The plot methods allow the user to check that the slope heuristics can be applied confidently.

Usage

plot(x,newwindow=TRUE,ask=TRUE) for [capushe](#).

plot(x,newwindow=TRUE) for [DDSE](#) and [Djump](#).

Arguments

x	Output of DDSE , Djump or capushe .
newwindow	If newwindow=TRUE, a new window is created for each plot.
ask	If ask=TRUE, plot waits for the user to press a key to display the next plot (only for the class capushe).

Details

The graphical window of DDSE is composed of three graphics (see [DDSE](#) for more details):

left The left plot shows $-\gamma_n(\hat{s}_m)$ with respect to the penalty shape values.

topright Successive slope values $\hat{\kappa}(p)$.

bottomright The bottomright plot shows the selected models $\hat{m}(p)$ with respect to the successive slope values. The plateau in blue is selected.

The graphical window of Djump shows the complexity $C_{m(\kappa)}$ of the selected model with respect to κ . $\hat{\kappa}^{dj}$ corresponds to the greatest jump. κ_{opt} is defined by $\kappa_{opt} = slope \times \hat{\kappa}^{dj}$. The red line represents the slope interval computed by the DDSE algorithm (only for capushe). See [Djump](#) for more details.

Methods

`signature(x = "Capushe")` This graphical function displays the DDSE plot and the Djump plot.

`signature(x = "DDSE")` This graphical function displays the [DDSE](#) plot.

`signature(x = "Djump")` This graphical function displays the [Djump](#) plot.

Note

Use `newwindow=FALSE` to produce a PDF files (for an object of class `capushe`, use moreover `ask=FALSE`).

validation

validation

Description

`validation` checks that the slope heuristics can be applied confidently.

Usage

```
validation(x, data2, ...)
```

Arguments

- | | |
|--------------------|--|
| <code>x</code> | <code>x</code> must be an object of class capushe or DDSE , in practice an output of the capushe function or the DDSE function. |
| <code>data2</code> | <code>data2</code> is a matrix or a <code>data.frame</code> with four columns of the same length and each line corresponds to a model: <ol style="list-style-type: none"> 1. The first column contains the model names. 2. The second column contains the penalty shape values. 3. The third column contains the model complexity values. 4. The fourth column contains the minimum contrast value for each model. |
| <code>...</code> | <ul style="list-style-type: none"> • If <code>newwindow==TRUE</code>, a new window is created for the plot. |

Details

The validation function plots the additional and more complex models data2 to check that the linear relation between the penalty shape values and the contrast values (which is recorded in x) is valid for the more complex models.

Author(s)

Vincent Brault

References

<http://www.math.univ-toulouse.fr/~maugis/CAPUSHE.html>

<http://www.math.u-psud.fr/~brault/capushe.html>

Article: Baudry, J.-P., Maugis, C. and Michel, B. (2011) Slope heuristics: overview and implementation. *Statistics and Computing*, to appear. doi: 10.1007/s11222-011-9236-1

See Also

[capushe](#) for a more general model selection function including [AIC](#), [BIC](#), the [DDSE](#) algorithm and the [Djump](#) algorithm.

Examples

```
data(datapartialcapushe)
capushepartial=capushe(datapartialcapushe)
data(datavalidcapushe)
validation(capushepartial,datavalidcapushe) ## The slope heuristics should not
## be applied for datapartialcapushe.
data(datacapushe)
plot(capushe(datacapushe))
```

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